

## Abstract

Electro vibration creates tactile sensations by modulating the friction between the skin and an insulated conductive surface powered by time-varying high-voltage signals [1]. This technology has been used extensively with touchscreens and occasionally with everyday objects. We present an exploration of electro vibration beyond the fingertip.

We first explored the design space and feasibility of electro vibrating clothing and wearables, before pivoting to its use on rigid objects that our palms brush against. We then sketched an electro vibrating keyboard that stimulates the palms. To better understand its capabilities, we conducted a psychophysical study to compare the detection thresholds of electro vibration at the palm and the fingertip. We found no statistically significant difference, which suggests that the palm is an appropriate target for electro vibration.

This work was originally published at the 2022 IEEE Haptics Symposium [2].

## DESIGN SPACE EXPLORATION

### Electro vibrating Clothing and Wearables

Preliminary experimentations with haptic sketches showed that electro vibration is strongest and most perceptible on the palm and fingertips, and slightly weaker on the wrist. We also found that electro vibration is difficult to produce on clothing because of its flexibility and that its feedback is frequently masked by other haptic cues present in clothing and wearables.



Figure 1. Mock-up of flexible electro vibrating surfaces.



Figure 2. Sketch of electro vibrating watch with cut capacitive plates.

### Electro vibrating Objects

We decided to pursue interactive designs in which the palm naturally brushes against the surface of everyday things. We focused our initial inquiry on the surface below a keyboard.



Figure 3. Sketch of electro vibrating keyboard.

## PSYCHOPHYSICAL EXPERIMENT

### Experimental Apparatus

An electro vibrating surface made of a capacitive touchpad (3M) was driven by a signal generator. A load cell was installed under the electro vibrating surface so that the force applied by the finger or palm could be measured.



Figure 4. Experimental setup.

### Procedure

The study (N=14) followed the same methods as [4] and used an adaptive staircase approach to estimate the absolute detection threshold at 5 frequencies (15, 30, 60, 120, and 240 Hz) on the fingertip and palm.

### Results

While we observed a higher threshold at the palm for 10/14 participants, a one-way repeated measures ANOVA failed to show a statistically significant difference between the fingertip and the palm ( $F(1, 26) = 2.252, p = 0.145$ ).

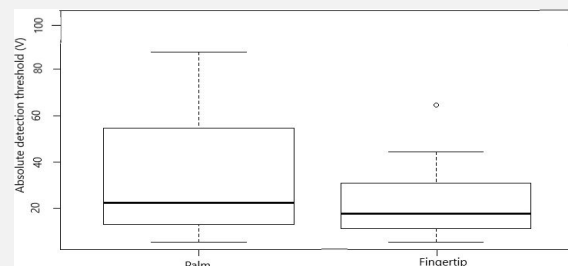


Figure 5. Absolute detection thresholds across participants.

## Conclusion

The design space and feasibility of electro vibration on clothing, wearables, and smart items were initially investigated. We discovered that the palm is very sensitive to electro vibration and turned our attention to objects that the palm brushes against, such as a keyboard. We then conducted an experiment to compare the detection threshold of electro vibration at the fingertip and the palm. Our results indicate that the sensitivity of the palm to electro vibration is similar to that of the fingertip.

## References

- [1] O. Bau, I. Poupyrev, A. Israr, and C. Harrison. Teslatouch: electro vibration for touch surfaces. In Proc. ACM UIST'10, pp. 283–292, 2010
- [2] B. Friaa and V. Levesque. A conceptual and experimental exploration of electro vibration on the palm and the body. In Proc. IEEE Haptics Symposium 2022, 2022
- [3] Y. Vardar, B. Guclu, and C. Basdogan. Effect of waveform on tactile perception by electro vibration displayed on touch screens. IEEE Transactions on Haptics, 10(4):488–499, 2017.

# Exploring Electro vibration on the Palm and the Body

Balkiss Friaa\*

École de technologie supérieure

Vincent Lévesque†

École de technologie supérieure

## ABSTRACT

We present an exploration of electro vibration beyond the fingertip. We first explored the design space and feasibility of electro vibrating clothing and wearables, before pivoting to its use on rigid objects that our palms frequently brush against. We then conceptualized and sketched an electro vibrating keyboard that produces tactile feedback on the palms. To better understand the capabilities of this keyboard, we conducted a psychophysical experiment with 14 participants to compare the detection thresholds of electro vibration at the palm and the fingertip. We found no statistically significant difference between the palm and fingertip, which suggests that the palm is an appropriate target for electro vibration. This work was originally published at the 2022 IEEE Haptics Symposium [4].

## 1 INTRODUCTION

Tactile sensations are created by modulating friction between the skin and an insulated conductive surface that is powered by time-varying high-voltage signals [3]. This technology has been applied to interactions with everyday objects as well as touchscreens (e.g., [2, 3]). We propose using electro vibration to stimulate areas of the hand and body other than the fingertip via clothing, wearables, and smart objects. We begin with a consideration of the design space and feasibility of incorporating electro vibration into clothing and wearables (Figures 1 and 2). Our attention then moves to rigid objects, with a particular focus on the palm as a sensitive site for electro vibration. We conclude our investigation with a concept for an electro vibrating keyboard that generates tactile feedback when the user's hands brush over its lower surface, either accidentally or intentionally (Figure 3).

While the effect of amplitude [7], frequency [5], and waveform [6] on the tactile perception of electro vibration at the fingertip has already been studied, we are unaware of research that investigates electro vibration perception at the palm. As a result, we conducted an experiment to determine how the electro vibration stimulus is perceived at the palm. For a variety of frequencies, the experiment examines the absolute thresholds of electro vibration perception at the fingertip and palm. Our results suggest that electro vibration should be easily perceived on a keyboard that stimulates the palms.

## 2 DESIGN SPACE EXPLORATION

### 2.1 Electro vibrating Clothing and Wearables

To examine the perception of electro vibration on the body, we created haptic sketches using flexible conductive materials such as copper or aluminium foil, as well as conductive textiles such as Velostat (Figure 1). We used a thin layer of insulating paint and 100V signals at frequencies ranging from 15 to 250 Hz to drive the materials. Current-limiting circuits (<5 mA), detachable connectors, and user switches were used as safety precautions.

Fabricating flexible electro vibrating surfaces with reliable insulation and accurate feedback at a voltage of 100V proved difficult. As

\*e-mail: balkiss.friaa.1@ens.etsmtl.ca

†e-mail: vincent.levesque@etsmtl.ca



Figure 1: Mock-up of flexible electro vibrating surfaces attached to the outer surface of a collar and cuffs.

as a result, we experimented with wearables made of multiple rigid surfaces (Figure 2). We found that glass cutting techniques can be used to cut capacitive glass plates (3M MicroTouch) without affecting their electrode structure.



Figure 2: Sketch of electro vibrating watch with cut capacitive plates.

Electro vibration is stronger and most perceptible on the palm and fingertips, and slightly weaker on the wrist, based on preliminary experimentations with these sketches. Because of the larger area of contact or the presence of hair, the arms, neck, and thighs produce a more subtle sensation and occasionally an unpleasant tingling. In addition, we have found that the sensations produced by the natural movement of the body against an electro vibrating clothing item or wearable are difficult to distinguish from other tactile cues such as the rubbing of clothing against the skin.

### 2.2 Electro vibrating Objects

Since the palm appears to respond strongly to electro vibration, we decided to pursue interactive designs in which the palm brushes against the surface of everyday things in a natural way. We focused our initial inquiry on the surface below a keyboard, such as a table beneath a keyboard or the lower surface of a laptop [5]. As we type on a keyboard, our hands often rest or slide on this surface, providing a chance for information to be transmitted via electro vibration. By combining a commercial keyboard (Logitech K380) with two capacitive plates (3M MicroTouch), we created a simple electro vibrating keyboard sketch (Figure 3).

## 3 EXPERIMENT

To better understand the possibilities of the proposed electro vibrating keyboard, a more extensive investigation comparing the tactile



Figure 3: Sketch of electrovibrating keyboard made with an off-the-shelf keyboard and two capacitive plates.

perception of electrovibration on the palm and fingertips is required. As a result, we conducted a psychophysical investigation to compare electrovibration perception on the fingertip and palm.

### 3.1 Experimental Apparatus

The experimental setup is illustrated in Figure 4. The signal generator consisted of a Raspberry Pi, a high precision AD/DA board, and a high-voltage amplifier. An electrovibrating surface made of a capacitive touchpad (3M MicroTouch) was driven by the signal generator. An area was left exposed while the rest was covered with tape to better regulate the location touched. To ensure the safety of the participants, certain safeguards were used. A 20-k $\Omega$  high-voltage resistor was used to limit the current to 5 mA. The output could be interrupted by pressing a large push button or releasing a foot pedal.

A load cell was installed under the electrovibrating surface so that the force applied by the finger or palm could be measured. The participants were asked to maintain a force between 0.1 and 0.6 N, which is within the typical range of forces used for tactile exploration [1]. During the experiment, participants used a keypad to enter their responses.

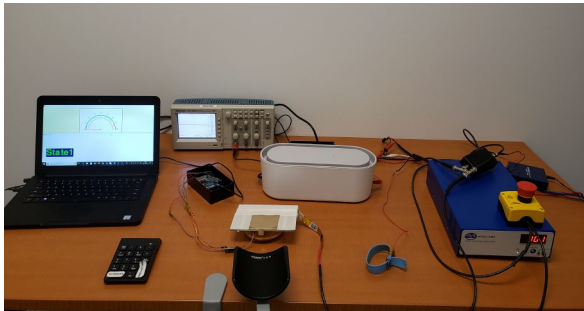


Figure 4: Experimental setup including electrovibrating surface, load cell, signal generator, keypad and computer monitor.

### 3.2 Procedure

We recruited 14 individuals, seven of which were female, with an average age of 27.5 years. The study, which followed the same methods as [6], involved evaluating the absolute detection thresholds of a sinusoidal signal at five frequencies (15, 30, 60, 120, and 240 Hz) using stimulating at two locations (fingertip and palm). These frequencies were produced randomly. The experiment was carried out utilizing the adaptive staircase method (one up/two down), which gives precise detection and discrimination thresholds with a small number of trials [3, 6].

### 3.3 Results

While we observed a higher detection threshold at the palm for 10 of the 14 participants, a one-way repeated measures ANOVA failed to show a statistically significant difference in absolute detection threshold between the fingertip and the palm ( $F(1, 26) = 2.252, p = 0.145$ ) (Figure 5).

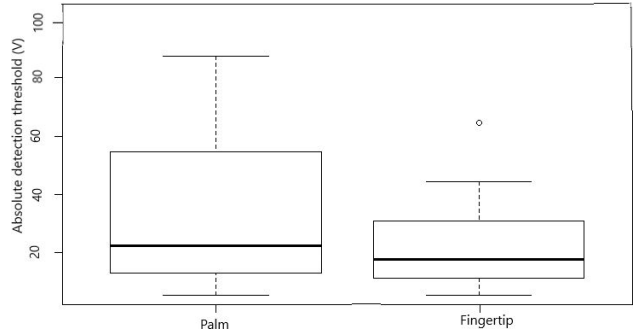


Figure 5: Absolute detection thresholds across participants.

## 4 CONCLUSION

The design space and feasibility of electrovibration on clothing, wearables, and smart items were initially investigated in this research. Electro-vibration is difficult to properly produce on clothing because of its flexibility and its feedback is frequently masked by other haptic cues present in clothing and wearables. However, we discovered that the palm is very sensitive to electrovibration and turned our attention to objects that the palm brushes against, such as a keyboard.

We then conducted an experiment to compare the detection threshold of electrovibration at the fingertip and the palm to better understand the capabilities of this keyboard. Our results indicate that the hand region has no statistically significant effect on the tactile sense of electrovibration. Implementing a fully functional prototype of the electrovibrating keyboard, creating exemplar applications to demonstrate the extra value of the haptic feedback this will create in real-world scenarios, and verifying the concept with user experiments will be the focus of our future effort.

### ACKNOWLEDGMENTS

The authors wish to thank Pascal E. Fortin. This work was supported by NSERC.

### REFERENCES

- [1] M. J. Adams, S. A. Johnson, P. Lefèvre, V. Lévesque, V. Hayward, T. André, and J.-L. Thonnard. Finger pad friction and its role in grip and touch. *Journal of The Royal Society Interface*, 10(80):20120467, 2013.
- [2] O. Bau and I. Poupyrev. Revel: tactile feedback technology for augmented reality. *ACM Transactions on Graphics*, 31(4):1–11, 2012.
- [3] O. Bau, I. Poupyrev, A. Israr, and C. Harrison. Teslatouch: electrovibration for touch surfaces. In *Proc. ACM UIST'10*, pp. 283–292, 2010.
- [4] B. Friaa and V. Lévesque. A conceptual and experimental exploration of electrovibration on the palm and the body. In *Proc. IEEE Haptics Symposium 2022*, 2022.
- [5] V. Levesque, J. M. Cruz-Hernandez, A. Weddle, and D. M. Birnbaum. System and method for simulated physical interactions with haptic effects, May 3 2016. US Patent 9,330,544.
- [6] Y. Vardar, B. Güçlü, and C. Basdogan. Effect of waveform on tactile perception by electrovibration displayed on touch screens. *IEEE transactions on haptics*, 10(4):488–499, 2017.
- [7] D. Wijekoon, M. E. Cecchinato, E. Hoggan, and J. Linjama. Electrostatic modulated friction as tactile feedback: Intensity perception. In *Proc. EuroHaptics 2012*, pp. 613–624, 2012.